





## 2<sup>nd</sup> Runner-up, Best Paper Award

Keyvan Majd for the paper

Certifiably-correct Control Policies for Safe Learning and Adaptation in Assistive Robotics at the

5<sup>th</sup> Robot Learning Workshop Trustworthy Robotics @NeurIPS 2022

9th December 2022

Julien Perez, NAVER LABS Europe

On behalf of the jury

Perez

DeepMind, Google and NAVER LABS Europe